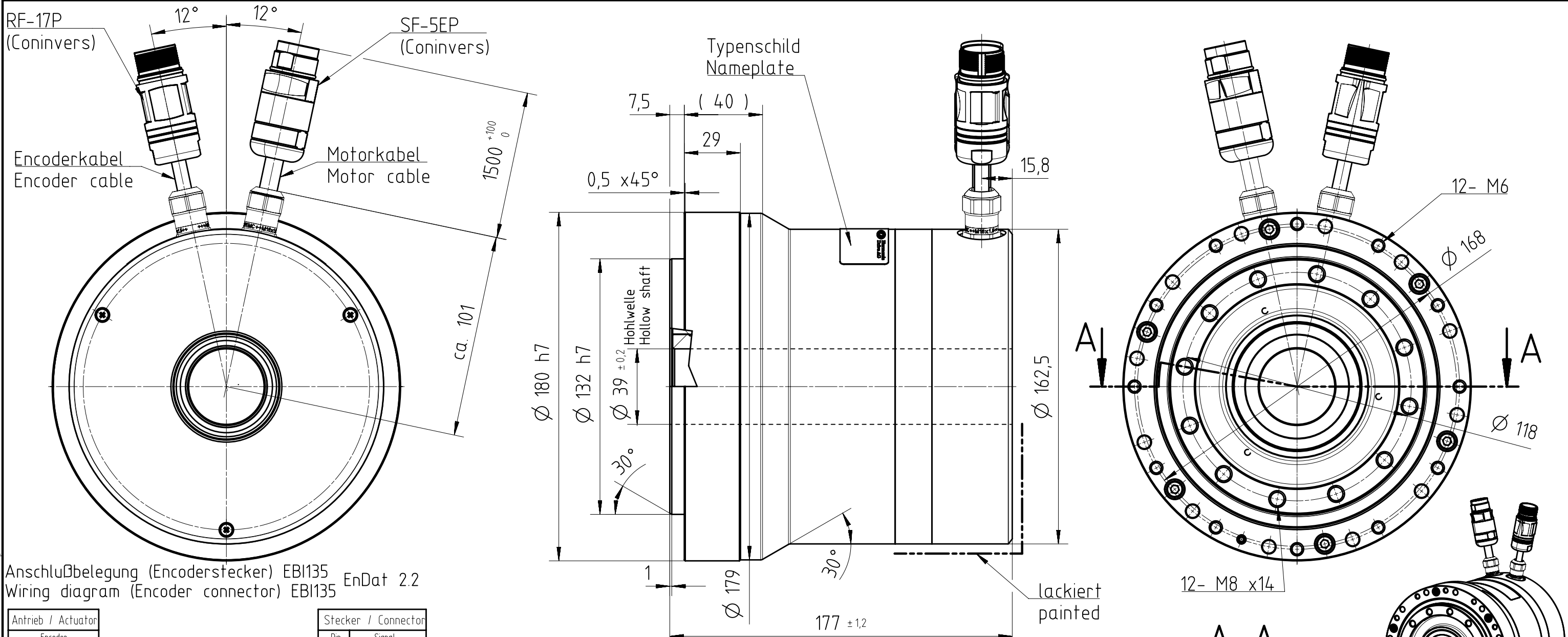
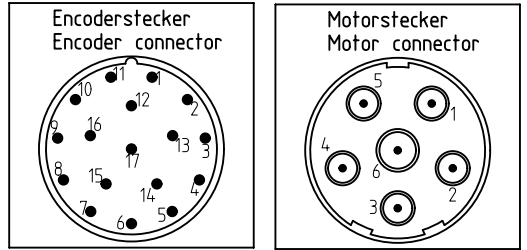


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Anschlußbelegung (Encoderstecker) EBI135 EnDat 2.2  
Wiring diagram (Encoder connector) EBI135

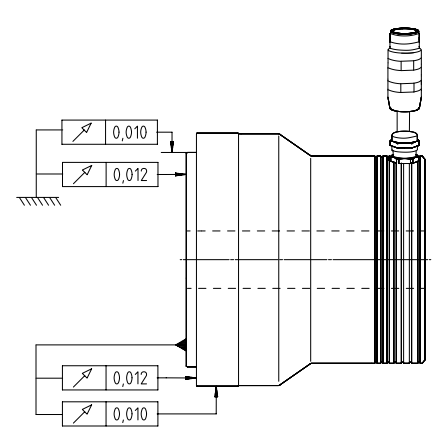
Antrieb / Actuator		Stecker / Connector	
Encoder		Pin	Signal
UBAT+	schwarz/black	17	inner shielding
		4	UBAT+
UBAT-	weiß/white	6	UBAT-
		11	n.c.
DATA+	rot/red	12	n.c.
		3	DATA+
DATA-	weiß/white	13	DATA-
		5	CLOCK+
CLOCK+	blau/blue	14	CLOCK-
		10	+Up
CLOCK-	weiß-rot (0,15mm²)	16	Sense+
		7	0V
Up+	white-red (0,15mm²)	15	Sense-
		8	TEMP+ (KTY)
0V	rot/red (0,5mm²)	9	TEMP- (KTY)
		1	n.c.
Motor	weiß-schwarz (0,15mm²)	2	n.c.
TEMP+ (KTY)	white-black (0,15mm²)		
TEMP- (KTY)	schwarz/black (0,5mm²)		
	weiß-braun		
	white-brown		
	weiß-blau		
	white-blue		



Anschlußbelegung (Motorstecker)  
Wiring diagram (motor connector)

Antrieb / Actuator		Stecker / Connector	
U		Pin	Signal
V	rot red	1	U
		2	V
PE	schwarz black	3	PE
		4	BRAKE+
* BRAKE+	grün-gelb green-yellow	5	BRAKE-
		6	W
* BRAKE-	weiß/white		
W	braun/brown		
	weiß white		

\* Brake is optional



**Harmonic Drive AG**

Allgemeintoleranzen  
ISO 2768-mH

Nennmaße < 0,5 --> ± 0,05  
Rundungshalbmesser < 0,5 --> ± 0,1

E

Maßstab: 1:2

Mat.-Nr.

Datum

Name

Zeichnungsnummer

Blatt 1

von 1

A3

Bezeichnung

CanisDrive-40A-xxx-AU-H-MZE-B

Zust. Änderung Datum Name Status: freigegeben Ers. f.: Ers. d.:

160

120

100 1028270

80

50

xxx Part-No.